Forschungspraxis, Assistant (Student)

Upgrading Movo's Platform

1) Installation of the new Force/Torque sensors

2) Installation of the new Real-sense Cameras

3) Installation of the new Grippers

4) Updating robot's URDF

Prerequisites

Strong robotic background

Strong C++ background

Previous similar experiments

Open for the long period contract (6 Months)

Contact

edwin.babaians@tum.de

Advisors

Edwin Babaians