Development of Interactive Segmentation Interface for Robotic Teleassistance

In this project we will use RGB-D sensor data coming from a robot and we will further develop our existing system that has a server-client architecture. The client side is a web-based GUI and the server side includes various interactive segmentation algorithms. We will conduct tests using the developed interface and an RGB-D sensor.

Prerequisites

- Basic knowledge of /experience with:
  
  - Python
  - ROS
  - Vue.js JavaScript Framework

- Motivation to learn the necessary tools and yield a successful work.

Contact

furkan.kaynar@tum.de

Please provide your CV and Transcript of Records for application.

Advisors

Hasan Furkan Kaynar